# AN8388S, AN8388SR

# 4 Ch. Linear Driver IC for CD Player

#### Overview

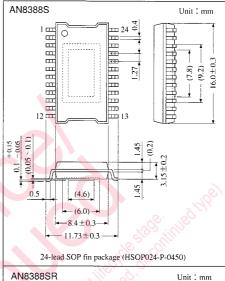
The AN8388S and AN8388SR employ 4 ch. H-bridge system that they are suitable for driving motor or actuator of CD player. Also they employ the surface mounting type package superior in radiation characteristics.

#### Features

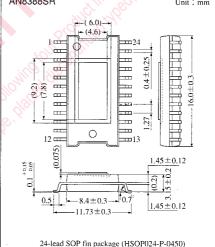
- Wide output D-range is available regardless of reference supply on the system.
- 4 ch. BTL Driver built-in. Particularly suitable for driver of actuator or motor of about  $8\,\Omega$  load.
- PC (Power Control) feature built-in
- Thermal shut down circuit (with hysteresis) built-in
- Control for proper heat of IC by separating the power supplies for signal line and output line.

## Application

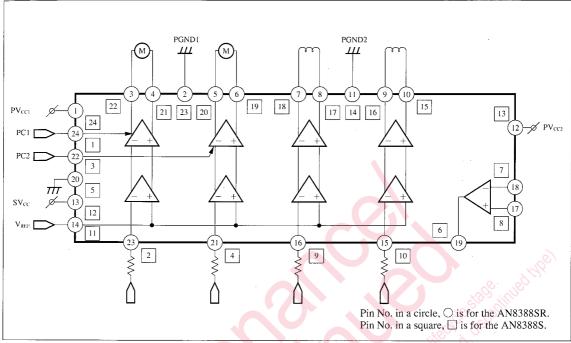
- CD player, CD-ROM
- For drive of motor











# ■ Absolute Maximum Ratings (Ta=25°C)

Parameter	Symbol	Rating	Unit
Supply Voltage	SV <sub>cc</sub>	160	V
Supply Current	$I_{CC}$	10M; 90	mA
Power Dissipation Note)	$P_{D}$	2083	mW
Operating Ambient Temperature	Topr	-30 ~ +85	°C
Storage Temperature	T <sub>stg</sub>	$-55 \sim +150$	°C

Note) For surface mounting on  $50 \times 50 \times 1.2$ mm glass epoxy board

## Recommended Operating Range ( $Ta = 25^{\circ}C$ )

	J \	~0′
Parameter	Symbol	Range
Operating Supply Voltage Range	V <sub>CC</sub>	4.5V ~ 15V

## ■ Electrical Characteristics ( $Ta = 25^{\circ}C \pm 2^{\circ}C$ )

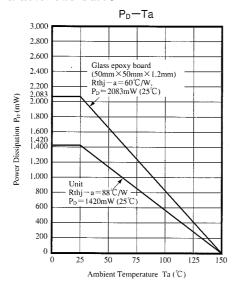
Parameter	Symbol	Condition	min.	typ.	max.	Unit		
Total Circuit Current	$I_{tot}$	$PV_{CC1} = PV_{CC2} = SV_{CC} = 8V$	10	25	40	mA		
Reset Circuit								
Reset Operation Release Supply Voltage	V <sub>RST</sub>	$R_L = 8 \Omega$			4.5	V		
Driver 1			,					
Input Offset Voltage	$V_{IOFI}$	$PV_{CC1} = PV_{CC2} = SV_{CC} = 8V$ $R_L = 8\Omega, R_{IN} = 10k\Omega$	-10	_	10	mV		
Output Offset Voltage	V <sub>OOF1</sub>	$PV_{CC1}=PV_{CC2}=SV_{CC}=8V$ $R_{L}=8\Omega, R_{IN}=10k\Omega$	-60		60	mV		
Gain (+)	G <sub>1+</sub>	$PV_{CC1}=PV_{CC2}=SV_{CC}=8V$ $R_{L}=8\Omega, R_{IN}=10k\Omega$	14	. 17	21	dB		
(+)(-) Relative Gain	⊿Gı	$PV_{CC1}=PV_{CC2}=SV_{CC}=8V$ $R_L=8\Omega, R_{IN}=10k\Omega$	-1.7	0	1.7	dB		
Limit Voltage (+)	V <sub>LI+</sub>	$PV_{CC1} = PV_{CC2} = SV_{CC} = 8V$ $R_L = 8\Omega, R_{IN} = 10k\Omega$	4.4	4.9	5.4	V		
Limit Voltage (-) Note 1)	V <sub>Ll</sub> -	$PV_{CC1} = PV_{CC2} = SV_{CC} = 8V$ $R_L = 8\Omega, R_{IN} = 10k\Omega$	0.93	1.0	1.07	-		
Dead Zone Width	$V_{DZI}$	$PV_{CC1} = PV_{CC2} = SV_{CC} = 8V$ $R_L = 8\Omega, R_{IN} = 10k\Omega$	-10	<u>}-</u>	20	mV		
PC Operation Threshold H	$V_{PCIH}$	$PV_{CC1} = PV_{CC2} = SV_{CC} = 8V$ $R_L = 8\Omega, R_{IN} = 10k\Omega$	3	30	35 Hilling	V		
Drivers 2 to 4								
Input Offset Voltage	V <sub>IOF</sub>	$PV_{CC1} = PV_{CC2} = SV_{CC} = 8V$ $R_L = 8\Omega, R_{IN} = 10k\Omega$	-10	100 p	10	mV		
Output Offset Voltage	V <sub>OOF</sub>	$PV_{CC1} = PV_{CC2} = SV_{CC} = 8V$ $R_L = 8\Omega, R_{IN} = 10k\Omega$	-60	94	60	mV		
Gain (+)	G+	$PV_{CC1} = PV_{CC2} = SV_{CC} = 8V$ $R_L = 8\Omega, R_{IN} = 10k\Omega$	14	17	21	dB		
(+)(-)Relative Gain	⊿G	$PV_{CC1} = PV_{CC2} = SV_{CC} = 8V$ $R_L = 8\Omega, R_{IN} = 10k\Omega$	0.93	1.0	1.07			
Limit Voltage (+) Note 2)	$V_{L+}$	$PV_{CC1} = PV_{CC2} = SV_{CC} = 8V$ $R_L = 8\Omega, R_{IN} = 10k\Omega$	0.93	1.0	1.07			
Limit Voltage (-) Note 1)	$V_{L-}$	$PV_{CC1} = PV_{CC2} = SV_{CC} = 8V$ $R_L = 8\Omega, R_{IN} = 10k\Omega$	0.93	1.0	1.07			
Dead Zone Width	$V_{DZ}$	$PV_{CC1} = PV_{CC2} = SV_{CC} = 8V$ $R_L = 8\Omega, R_{IN} = 10k\Omega$	-10		20	mV		
PC Operation Threshold H	$V_{PCH}$	$PV_{CC1} = PV_{CC2} = SV_{CC} = 8V$ $R_L = 8\Omega, R_{IN} = 10k\Omega$	3		—	· V		
Operational amplifier Offset Voltage	V <sub>OF</sub> -OP	$PV_{CC1} = PV_{CC2} = SV_{CC} = 8V$	-40		40	mV		
Heat Protection Circuit	Naj Co	2).						
Operation Temperature Equilibrium Value Note 3)	Ттнр		( — )	(160)	( — )	$^{\circ}$		
Operation Temperature Hysteresis Width Note 3)	△T <sub>THD</sub>		( )	( 65)	( — )	${\mathbb C}$		

Note1) Relative voltage ratio of limit voltage (+) for each channel.

Note2) Relative voltage ratio of limit voltage (+) of Drivers 2 to 4 to limit voltage (+) of Driver 1

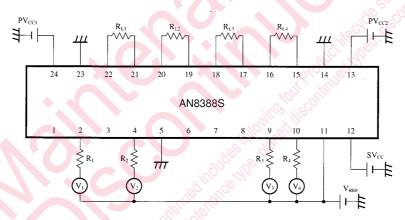
Note3) Characteristic value in parentheses is a reference value for design but not a guaranteed value.

#### ■ Characteristic Curve



### Cautions for use

#### AN8388S



When the AN8388S is used, take into account the following cautions and follow the power dissipation characteristic curve.

(1) Load current, IPI flowing in loads RLI and RL2 is supplied through Pin 24.

$$I_{PI} = \frac{|V_{22-21}|}{R_{L1}} + \frac{|V_{20-19}|}{R_{L2}}$$

(2) Load current, IP2 flowing in loads RL3 and RL4 is supplied through Pin 13.

$$I_{P2} = \frac{|V_{18-17}|}{R_{L3}} + \frac{|V_{16-15}|}{R_{L4}}$$

(3) Dissipation increase ( $\Delta P_d$ ) inside the IC (power output stage) caused by loads  $R_{L1}$ ,  $R_{L2}$ ,  $R_{L3}$ , and  $R_{L4}$  is as follows:

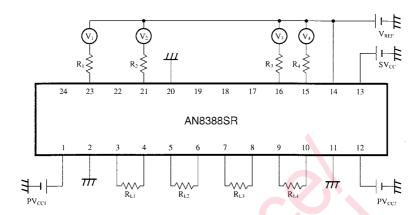
$$\begin{split} \varDelta P_{d} &= (PV_{CC1} - |V_{22-21}|) \times \frac{|V_{22-21}|}{R_{Li}} + (PV_{CC1} - |V_{20-19}|) \times \frac{|V_{20-19}|}{R_{L2}} \\ &+ (PV_{CC2} - |V_{18-17}|) \times \frac{|V_{18-17}|}{R_{L3}} + (PV_{CC2} - |V_{16-15}|) \times \frac{|V_{16-15}|}{R_{L4}} \end{split}$$

(4) Dissipation increase (△P<sub>S</sub>) inside the IC (signal block supplied from Pin②) caused by loads R<sub>L1</sub>, R<sub>L2</sub>, R<sub>L3</sub>, and R<sub>L4</sub> is almost as follows:

(5) Dissipation increase inside the IC during driver running is  $\Delta P_d + \Delta P_s$ .

## Cautions for use

#### AN8388SR



When the AN8388SR is used, take into account the following cautions and follow the power dissipation characteristic curve.

(1) Load current, IPI flowing in loads RLI and RL2 is supplied through Pin 1.

$$I_{PI} = \frac{|V_{3-4}|}{R_{LI}} + \frac{|V_{5-6}|}{R_{L2}}$$

(2) Load current, I<sub>P2</sub> flowing in loads R<sub>L3</sub> and R<sub>L4</sub> is supplied through Pin 2.

$$I_{P2} = \frac{\mid V_{7-8} \mid}{R_{L3}} + \frac{\mid V_{9-10} \mid}{R_{L4}}$$

(3) Dissipation increase (△P<sub>d</sub>) inside the IC (power output stage) caused by loads R<sub>L1</sub>, R<sub>L2</sub>, R<sub>L3</sub> and R<sub>L4</sub> is as follows:

$$\begin{split} \varDelta P_d &= (PV_{CC1} - |V_{3-4}|) \times \frac{|V_{3-4}|}{R_{L1}} + (PV_{CC1} - |V_{5-6}|) \times \quad \frac{|V_{5-6}|}{R_{L2}} \\ &+ (PV_{CC2} - |V_{7-8}|) \times \frac{|V_{7-8}|}{R_{L3}} + (PV_{CC2} - |V_{9-10}|) \times \quad \frac{|V_{9-10}|}{R_{L4}} \end{split}$$

(4) Dissipation increase (△P<sub>S</sub>) inside the IC (signal block supplied from Pin<sup>(3)</sup>) caused by loads R<sub>L1</sub>, R<sub>L2</sub>, R<sub>L3</sub> and R<sub>L4</sub> is almost as follows:

(5) Dissipation increase inside the IC during driver running is,  $\Delta P_d + \Delta P_s$ .



## ■ Pin Description

Pin No.		DC voltage		D: D			
AN8388S	AN8388SR	Symbol	I/O	(V <sub>CC</sub> /8V)	Pin Description	Equivalent Circuit	
1	24	PC1	I	0V	PC (power cut) input pin controlling the output of ② and ②	①	
3	22	PC2	I	0V	PC (power cut) input pin controlling the output of (9) and (20)	***************************************	
2	23	IN1	I	2.5V	Error input pin of Driver 1	Ø Ø	
4	21	IN2	I	2.5V	Error input pin of Driver 2	2 or 4 or 9	
9	16	IN3	I	2.5V	Error input pin of Driver 3	or \$500	
10	15	IN4	I	2.5V	Error input pin of Driver 4	10 #	
7	18	IN-		_ v	Reverse rotation input pin of operational amplifier	sv <sub>cc</sub>	
8	17	IN+	I	Maintenance Maintenance	Normal rotation input pin of operational amplifier	8	
12	13	SV <sub>CC</sub>	I	8V	$SV_{CC}$ pin for control circuit of driver, not connected to power $V_{CC}$ pin.	(12)————————————————————————————————————	
5	20	SGND	I	0V	SGND pin for control circuit of driver	5 777	

Note) The pin numbers shown in the equivalent circuit diagram are only for the AN8388S. For the AN8388SR, they must be replaced.

# Pin Description (Cont.)

Pin		Symbol	I/O	DC voltage	Pin Description	Equivalent Circuit
AN8388S	AN8388SR	J		(V <sub>CC</sub> /8V)		
6	19	ОРО	0	— v	Operational amplifier output pin	
11	14	$V_{ m REF}$	I	2.5V	V <sub>REF</sub> input pin	
22	3	DI-	0	0V	Reverse rotation output pin of Driver 1	(PV <sub>(C)</sub> )
21	4	D1+	0	0V	Normal rotation output pin of Driver 1	<b>T</b>
20	5	D2-	0	0V	Reverse rotation output pin of Driver 2	
19	6	D2+	0	0V	Normal rotation output pin of Driver 2	discontinuity of the second
18	7	D3-	0	0V	Reverse rotation output pin of Driver 3	
17	8	D3+	0	0V	Normal rotation output pin of Driver 3	
16	9	D4-	0	0V	Reverse rotation output pin of Driver 4	20 16 T 19 15 or or
15	10	D4+	0	0V	Normal rotation output pin of Driver 4	②® <sup>#</sup> <sup>#</sup> ② Ū
24	1	PV <sub>cc1</sub>	I	8V	Power $V_{cc}$ pin, supplying the current flowing for output power transistors of $\textcircled{1}$ , $\textcircled{2}$ , and $\textcircled{2}$	(13) or (24)
13	12	PV <sub>CC2</sub>	Dist	8V	Power $V_{CC}$ pin, supplying the current flowing for output power transistors of $(3)$ , $(6)$ , $(7)$ , and $(8)$	
23	2	PGND1	·I	0V	PGND pin for output transistors of (9, 20, 2), and 22	14 m
14	11	PGND2	I	0V	PGND pin for output transistors of (15), (16), (17), and (18)	23

Note) The pin numbers shown in the equivalent circuit diagram are only for the AN8388S. For the AN8388SR, they must be replaced.



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